

# $\left(\frac{G^{\prime}}{G}\right)$-expansion method to seek traveling wave solutions for some Fractional Nonlinear PDEs arising in natural sciences 

Medjahed Djilali ${ }^{1}$, Ali Hakem ${ }^{\text {b }}$<br>${ }^{\text {a }}$ Department of Mathematics, Faculty of Science and Technology, University of Relizane, 48000 Relizane, Algeria.<br>${ }^{b}$ Laboratory ACEDP, Djillali Liabes University, 22000 SIDI-BEL-ABBES, Algeria.


#### Abstract

The $\left(\frac{G^{\prime}}{G}\right)$-expansion method with the aid of symbolic computational system can be used to obtain the traveling wave solutions (hyperbolic, trigonometric and rational solutions) for nonlinear time-fractional evolution equations arising in mathematical physics and biology. In this work, we will process the analytical solutions of the time-fractional classical Boussinesq equation, the time-fractional Murray equation, and the space-time fractional Phi-four equation. With the fact that the method which we will propose in this paper is also a standard, direct and computerized method, the exact solutions for these equations are obtained.


Keywords: Exact solutions Traveling wave solutions Boussines equation Murray equation Phi-four equation.
2010 MSC: 47J35, 35R11, 35C07, 83C15

## 1. Introduction

The analytic treatment of nonlinear evolution equations have attracted attention of many mathematicians and physicists. Many authors are interested in the research of the exact solutions 1, 2, 3, 4, 4, 6, 7, 8, [9, 10, 11, 12, 13, because the exact solutions of nonlinear evolution equations are the key tool to understand the various physical phenomena that govern the real world today in many fields such as plasma physics, fluid

[^0]physics, quantum field theory, biophysics, chemical kinematics, geochemistry, electricity and mathematical biology.

In recent years, with the assist of many computation packages like Mathematica 11, many powerful analytical methods to construct exact solutions for nonlinear partial differential equations have been proposed, the tanh function method [5, 7, 14], the extended tanh method [14, 15], the sine-cosine method [14], the rational method, extended rational expansion method [12], the Lie group method [16, [17], Weierstrass elliptic function method [18], Exp-function method [19], the residual powers series (RPS) method [20], the modified simple equation (MSE) method [1], the generalized Kudryashov method [10], Cole-Hopf transformation constrictive method [21], He's semi-inverse method [22], the auxiliary differential equation method [8, the Backlund transformation method [23], the Hirota's bi linear transformation method [9] and others. More recently, the $\left(\frac{G^{\prime}}{G}\right)$-expansion method [11, 15, 24, 25, 26, 27, 28, 29, 30, 31, 32] has been proposed to obtain traveling wave solutions. This method is firstly proposed by Wang et al. [30] for which the traveling wave solutions of the nonlinear evolution equations are obtained 33.
By using this well known method, our main objective of this paper is to investigate the exact solutions for the following three generalized fractional nonlinear evolution equations, first the generalized time-fractional classical Boussinesq equation in the form:

$$
D_{t}^{2 \alpha} u+\epsilon u_{4 x}+\gamma u_{2 x}+\beta u u_{2 x}+\beta\left(u_{x}\right)^{2}=0
$$

where $\epsilon, \gamma, \beta \in \mathbb{R}^{*}, \frac{1}{2}<\alpha \leq 1$ and $D_{t}^{2 \alpha} u:=\frac{\partial^{2 \alpha} u(x, t)}{\partial t^{2 \alpha}}$ in the sense of Caputo derivative.
In the particular case $\alpha=1$ see [8, 9, 12, 16, 17, 22, 23, $34,35,36]$ : this very famous nonlinear evolution equation was developed to describe the motion of water with small amplitude and long wave [22]. The second considerable equation is the generalized time-fractional Murray equation in the form:

$$
D_{t}^{\alpha} u-u_{2 x}-a u u_{x}-b u+c u^{2}=0
$$

where $a, b, c \in \mathbb{R}^{*}, D_{t}^{\alpha} u:=\frac{\partial^{\alpha} u(x, t)}{\partial t^{\alpha}}$ in the sense of Caputo derivative and $0<\alpha \leq 1$.
For the case $\alpha=1$ see [3, 4, 21, 37, 38, 39, 40], it is an important equation which was first suggested to describe the propagation of genes, and it was established later that this equation also generalizes a great number of well known nonlinear second-order evolution equations describing various processes in biology [38, 39].
Finally, we consider the Generalized space-time fractional Phi-four equation in the form:

$$
D_{t}^{2 \alpha} u-p D_{x}^{2 \beta} u-q u+r u^{3}=0
$$

where $p, q, r \in \mathbb{R}_{+}^{*}, D_{t}^{2 \alpha} u:=\frac{\partial^{2 \alpha} u(x, t)}{\partial t^{2 \alpha}}, D_{t}^{2 \beta} u:=\frac{\partial^{2 \beta} u(x, t)}{\partial t^{2 \beta}}$ in the sense of Caputo derivative and $\frac{1}{2}<\alpha \leq$ $1, \frac{1}{2}<\beta \leq 1$.
Many authors treat the case $\alpha=\beta=1$ in several contexts [1, 10, 14, 18, 19, 41, 42, 43, 44, the PHI-four equation is considered as a particular form of the Klein-Gordon equation that model phenomenon in particle physics where kink and anti-kink solitary waves interact [14].

### 1.1. Caputo derivative

The Caputo derivative of order $\alpha$ is defined by the formula [45, 46, 47, 48, 49]:

$$
D_{*}^{\alpha} f(t)=\left\{\begin{array}{l}
\frac{1}{\Gamma(m-\alpha)} \int_{0}^{t}(t-\tau)^{m-\alpha-1} f^{(m)}(\tau) d \tau, \quad \text { if } m-1<\alpha<m  \tag{1}\\
\frac{d^{m}}{d t^{m}} f(t), \quad \text { if } \alpha=m
\end{array}\right.
$$

where $m \in \mathbb{N}^{*}$ and $\Gamma($.$) denotes the Gamma function$
defined by $\Gamma(x)=\int_{0}^{\infty} t^{x-1} e^{-t} d t, \quad x>0$.

The important properties of the Caputo derivative that will be used in this paper are :

$$
\begin{gather*}
D_{t}^{\alpha} t^{\beta}=\frac{\Gamma(1+\beta)}{\Gamma(1+\beta-\alpha)} t^{\beta-\alpha}  \tag{2}\\
D_{t}^{\alpha}[f(g(t))]=f_{g}^{\prime}(g(t)) D_{t}^{\alpha} g(t)=D_{g}^{\alpha} f(g(t))\left[g_{t}^{\prime}(t)\right]^{\alpha},  \tag{3}\\
d^{\alpha} h(t)=\Gamma(1+\alpha) d h(t) . \tag{4}
\end{gather*}
$$

## 2. Description of the $\left(\frac{G^{\prime}}{G}\right)$-expansion method

The general nonlinear Time-Fractional evolution equation, say in two independent variables x and t , is given by

$$
\begin{equation*}
P\left(u, D_{t}^{\alpha} u, u_{x}, D_{t}^{2 \alpha} u, u_{x x}, D_{t}^{\alpha} u_{x}, \ldots\right)=0, \quad 0<\alpha \leq 1 \tag{5}
\end{equation*}
$$

where $u=u(x, t)$ is an unknown function, $P$ is a polynomial of $u$ and its partial fractional derivatives, in which the nonlinear terms and the highest order derivatives are included. To find the traveling wave solution of Eq. (5) by $\left(\frac{G^{\prime}}{G}\right)$-expansion method, we follow the following steps

- Step 1: To obtain exact traveling wave solution, the following fractional complex transformation [50, 51, 52, 53] has been applied

$$
\begin{equation*}
u(x, t)=U(\xi), \quad \xi=k x-\frac{\omega t^{\alpha}}{\Gamma(1+\alpha)}, \quad \text { or } \quad \xi=\frac{k x^{\beta}}{\Gamma(1+\beta)}-\frac{\omega t^{\alpha}}{\Gamma(1+\alpha)} \tag{6}
\end{equation*}
$$

where $k, \omega \in \mathbb{R}^{*}$ are constants to be determined latter. Then, the $\mathrm{Eq}(5)$ is reduced to the following nonlinear ordinary differential equation

$$
\begin{equation*}
P\left(U,-\omega U^{\prime}, k U, \omega^{2} U^{\prime \prime}, k^{2} U^{\prime \prime},-\omega k U^{\prime}, \ldots\right)=0 \tag{7}
\end{equation*}
$$

where $U^{(i)}=U_{i \xi}$.

- Step 2: Assuming that the solution of Eq. (7) can be expressed as a finite power series of the form:

$$
\begin{equation*}
U(\xi)=\sum_{n=0}^{N} a_{n}\left(\frac{G^{\prime}(\xi)}{G(\xi)}\right)^{n} \tag{8}
\end{equation*}
$$

where $a_{0}, a_{1}, \ldots a_{N}\left(a_{N} \neq 0\right)$ are constants to be determined later.

1. Let $G=G(\xi)$ satisfies the second order LODE in the form:

$$
\begin{equation*}
G^{\prime \prime}+\lambda G^{\prime}+\mu G=0 \tag{9}
\end{equation*}
$$

where $\lambda, \mu$ are constants to be discuss later.
The general solutions of (9) can be written in the forms as follow

$$
G(\xi)=\left\{\begin{array}{l}
e^{\frac{1}{2}(-\lambda) \xi}\left(A_{2} \sinh \left(\frac{1}{2} \xi \sqrt{\lambda^{2}-4 \mu}\right)+A_{1} \cosh \left(\frac{1}{2} \xi \sqrt{\lambda^{2}-4 \mu}\right)\right), \quad \lambda^{2}-4 \mu>0  \tag{10}\\
e^{\frac{1}{2}(-\lambda) \xi}\left(A_{2} \sin \left(\frac{1}{2} \xi \sqrt{4 \mu-\lambda^{2}}\right)+A_{1} \cos \left(\frac{1}{2} \xi \sqrt{4 \mu-\lambda^{2}}\right)\right), \quad \lambda^{2}-4 \mu<0 \\
\left(A_{2} \xi+A_{1}\right) e^{\frac{1}{2}(-\lambda) \xi}, \quad \lambda^{2}-4 \mu=0
\end{array}\right.
$$

it yields

$$
\frac{G^{\prime}}{G}=\left\{\begin{array}{l}
\frac{\sqrt{\lambda^{2}-4 \mu}}{2}\left[\frac{A_{1} \sinh \left(\frac{1}{2} \xi \sqrt{\lambda^{2}-4 \mu}\right)+A_{2} \cosh \left(\frac{1}{2} \xi \sqrt{\lambda^{2}-4 \mu}\right)}{A_{2} \sinh \left(\frac{1}{2} \xi \sqrt{\lambda^{2}-4 \mu}\right)+A_{1} \cosh \left(\frac{1}{2} \xi \sqrt{\lambda^{2}-4 \mu}\right)}\right]-\frac{\lambda}{2}, \quad \lambda^{2}-4 \mu>0,  \tag{11}\\
\frac{\sqrt{4 \mu-\lambda^{2}}}{2}\left[\frac{A_{2} \cos \left(\frac{1}{2} \xi \sqrt{4 \mu-\lambda^{2}}\right)-A_{1} \sin \left(\frac{1}{2} \xi \sqrt{4 \mu-\lambda^{2}}\right)}{A_{2} \sin \left(\frac{1}{2} \xi \sqrt{4 \mu-\lambda^{2}}\right)+A_{1} \cos \left(\frac{1}{2} \xi \sqrt{4 \mu-\lambda^{2}}\right)}\right]-\frac{\lambda}{2}, \quad \lambda^{2}-4 \mu<0, \\
\frac{A_{2}}{A_{2} \xi+A_{1}}-\frac{\lambda}{2}, \quad \lambda^{2}-4 \mu=0,
\end{array}\right.
$$

where $A_{1}$ and $A_{2}$ are arbitrary constants.
2. Let $G=G(\xi)$ satisfies the Riccati equation in the form

$$
\begin{equation*}
G^{\prime}=\mu G^{2}+\nu G+\lambda \tag{12}
\end{equation*}
$$

where $\mu, \nu, \lambda$ are constants and $\mu \neq 0, \nu \neq 0$.
The general solutions of (12) ( when $\lambda=0$ ) can be written in the form as follow

$$
\begin{equation*}
G(\xi)=-\frac{A \nu(\sinh (\nu \xi)+\cosh (\nu \xi))}{A \mu(\sinh (\nu \xi)+\cosh (\nu \xi))-1} \tag{13}
\end{equation*}
$$

it yields

$$
\begin{equation*}
\frac{G^{\prime}}{G}=-\frac{\nu}{A \mu(\sinh (\nu \xi)+\cosh (\nu \xi))-1} \tag{14}
\end{equation*}
$$

where $A$ is arbitrary constant $(A \neq 0)$.

- Step 3: The degree $N$ of the power series (8) is determined by considering the homogeneous balance between the nonlinear term in Eq. (7) and the highest-order derivative. Suppose the degree of $U(\xi)$ is $N$, then the degree of the other expression can be evaluated as follows:

$$
\begin{equation*}
D\left(U^{(p)}\right)=N+p, D\left(U^{p}\left(U^{(q)}\right)^{s}\right)=N p+s(N+q) \tag{15}
\end{equation*}
$$

- Step 4: Substituting Eq. (8) using Eq. (9) into Eq. (7). Then collecting the coefficients of like powers of $\left(\frac{G^{\prime}}{G}\right)^{n},(n=0,1,2, \ldots, N)$. A set of nonlinear algebraic equations is obtained, by equating each coefficient to zero. The resulting algebraic system is solved with the help of Mathematica 11 to get the values of unknown constants $a_{0}, a_{1}, \ldots a_{N}$ and $k, \omega$.
- Step 5: Since the general solution of (9) has been well known for us, then substituting $a_{n}, k, \omega$ and (14) into (8), we have three types of the Exact traveling wave solutions of the time-fractional nonlinear evolution equation (5).


## 3. The time-fractional classical Boussinesq equation

$$
\begin{equation*}
\frac{\partial^{2 \alpha} u(x, t)}{\partial t^{2 \alpha}}+\gamma \frac{\partial^{2} u(x, t)}{\partial x^{2}}+\beta u(x, t) \frac{\partial^{2} u(x, t)}{\partial x^{2}}+\beta\left(\frac{\partial u(x, t)}{\partial x}\right)^{2}+\epsilon \frac{\partial^{4} u(x, t)}{\partial x^{4}}=0 \tag{16}
\end{equation*}
$$

where $\epsilon, \gamma, \beta \in \mathbb{R}^{*}$, and $\frac{1}{2}<\alpha \leq 1$.
Using the fractional complex transformation $u(x, t)=U(\xi), \quad \xi=k x-\frac{\omega t^{\alpha}}{\Gamma(\alpha+1)}$, the (TFCBE) 16) is converted to the (NLODE)

$$
\begin{equation*}
\left(\omega^{2}+\gamma k^{2}\right) U^{\prime \prime}+\beta k^{2} \mathrm{UU}^{\prime \prime}+\beta k^{2}\left(U^{\prime}\right)^{2}+\epsilon k^{4} U^{(4)}=0 \tag{17}
\end{equation*}
$$

Balancing $\mathrm{U}^{(4)}$ with $\mathrm{UU}^{\prime \prime}$ in 17 gives $N+4=2 N+2$, hence $N=2$. We then suppose that 17 has the following formal solutions:

$$
\begin{equation*}
U(\xi)=a_{0}+a_{1}\left(\frac{G^{\prime}(\xi)}{G(\xi)}\right)+a_{2}\left(\frac{G^{\prime}(\xi)}{G(\xi)}\right)^{2} \tag{18}
\end{equation*}
$$

Substituting Equation (18) with using (9) into Equation (17) and collecting all terms with the same order of $\left(\frac{G^{\prime}}{G}\right)$ together, the left-hand sides of Equation 17 ) are converted into a polynomial in $\left(\frac{G^{\prime}}{G}\right)$. Setting each coefficient of each term to zero, we derive a set of algebraic equations for $a_{0}, a_{1}, a_{2}, k, \omega$.

$$
\begin{align*}
& a_{1} \lambda^{3} k^{4} \mu \epsilon+14 a_{2} \lambda^{2} k^{4} \mu^{2} \epsilon+8 a_{1} \lambda k^{4} \mu^{2} \epsilon+16 a_{2} k^{4} \mu^{3} \epsilon+a_{0} a_{1} \beta \lambda k^{2} \mu+a_{1}^{2} \beta k^{2} \mu^{2} \\
& +2 a_{0} a_{2} \beta k^{2} \mu^{2}+a_{1} \gamma \lambda k^{2} \mu+2 a_{2} \gamma k^{2} \mu^{2}+a_{1} \lambda \mu \omega^{2}+2 a_{2} \mu^{2} \omega^{2}=0, \\
& a_{1} \lambda^{4} k^{4} \epsilon+30 a_{2} \lambda^{3} k^{4} \mu \epsilon+22 a_{1} \lambda^{2} k^{4} \mu \epsilon+120 a_{2} \lambda k^{4} \mu^{2} \epsilon+16 a_{1} k^{4} \mu^{2} \epsilon+a_{0} a_{1} \beta \lambda^{2} k^{2} \\
& +3 a_{1}^{2} \beta \lambda k^{2} \mu+6 a_{0} a_{2} \beta \lambda k^{2} \mu+6 a_{1} a_{2} \beta k^{2} \mu^{2}+2 a_{0} a_{1} \beta k^{2} \mu+a_{1} \gamma+k^{2} \lambda^{2}+6 a_{2} \gamma \lambda k^{2} \mu \\
& +2 a_{1} \gamma k^{2} \mu+a_{1} \lambda^{2} \omega^{2}+6 a_{2} \lambda \mu \omega^{2}+2 a_{1} \mu \omega^{2}=0, \\
& 16 a_{2} \lambda^{4} k^{4} \epsilon+15 a_{1} \lambda^{3} k^{4} \epsilon+232 a_{2} \lambda^{2} k^{4} \mu \epsilon+60 a_{1} \lambda k^{4} \mu \epsilon+136 a_{2} k^{4} \mu^{2} \epsilon+2 a_{1}^{2} \beta \lambda^{2} k^{2} \\
& +4 a_{0} a_{2} \beta \lambda^{2} k^{2}+15 a_{1} a_{2} \beta \lambda k^{2} \mu+3 a_{0} a_{1} \beta \lambda k^{2}+6 a_{2}^{2} \beta k^{2} \mu^{2}+4 a_{1}^{2} \beta k^{2} \mu+8 a_{0} a_{2} \beta k^{2} \mu \\
& +4 a_{2} \gamma \lambda^{2} k^{2}+3 a_{1} \gamma \lambda k^{2}+8 a_{2} \gamma k^{2} \mu+4 a_{2} \lambda^{2} \omega^{2}+3 a_{1} \lambda \omega^{2}+8 a_{2} \mu \omega^{2}=0,  \tag{19}\\
& 130 a_{2} \lambda^{3} k^{4} \epsilon+50 a_{1} \lambda^{2} k^{4} \epsilon+440 a_{2} \lambda k^{4} \mu \epsilon+40 a_{1} k^{4} \mu \epsilon+9 a_{1} a_{2} \beta \lambda^{2} k^{2}+14 a_{2}^{2} \beta \lambda k^{2} \mu+5 a_{1}^{2} \beta \lambda k^{2} \\
& +10 a_{0} a_{2} \beta \lambda k^{2}+18 a_{1} a_{2} \beta k^{2} \mu+2 a_{0} a_{1} \beta k^{2}+10 a_{2} \gamma \lambda k^{2}++2 a_{1} \gamma k^{2}+10 a_{2} \lambda \omega^{2}+2 a_{1} \omega^{2}=0, \\
& 330 a_{2} \lambda^{2} k^{4} \epsilon+60 a_{1} \lambda k^{4} \epsilon+240 a_{2} k^{4} \mu \epsilon+8 a_{2}^{2} \beta \lambda^{2} k^{2}+21 a_{1} a_{2} \beta \lambda k^{2} \\
& +16 a_{2}^{2} \beta k^{2} \mu+3 a_{1}^{2} \beta k^{2}+6 a_{0} a_{2} \beta k^{2}+6 a_{2} \gamma k^{2}+6 a_{2} \omega^{2}=0, \\
& 336 a_{2} \lambda k^{4} \epsilon++24 a_{1} k^{4} \epsilon+18 a_{2}^{2} \beta \lambda k^{2}+12 a_{1} a_{2} \beta k^{2}=0, \\
& 120 a_{2} k^{4} \epsilon+10 a_{2}^{2} \beta k^{2}=0 .
\end{align*}
$$

The resulting algebraic system $\sqrt{19}$ is solved with the help of Mathematica 11 to get the values of unknown constants $a_{0} ; a_{1} ; a_{2} ; k ; \omega$

$$
\begin{equation*}
\left\{a_{0} \rightarrow \frac{-\lambda^{2} k^{4} \epsilon-8 k^{4} \mu \epsilon-\gamma k^{2}-\omega^{2}}{\beta k^{2}}, a_{1} \rightarrow-\frac{12 k^{2} \lambda \epsilon}{\beta}, a_{2} \rightarrow-\frac{12 k^{2} \epsilon}{\beta}\right\} \tag{20}
\end{equation*}
$$

where $\lambda$ and $\mu$ are arbitrary constants.
By using Eqs. 20) , expression (18) can be written as:

$$
\begin{equation*}
U(\xi)=\frac{-\lambda^{2} k^{4} \epsilon-8 k^{4} \mu \epsilon-\gamma k^{2}-\omega^{2}}{\beta k^{2}}-\frac{12 k^{2} \lambda \epsilon}{\beta}\left(\frac{G^{\prime}(\xi)}{G(\xi)}\right)-\frac{12 k^{2} \epsilon}{\beta}\left(\frac{G^{\prime}(\xi)}{G(\xi)}\right)^{2} \tag{21}
\end{equation*}
$$

Now, using Eqs. (11) into (21), we have three kinds of traveling wave solutions of Eq. 16) as follows:

- case 1: $\lambda^{2}-4 \mu>0$, we get the hyperbolic function solutions of Eq. (16)

$$
\begin{align*}
u_{1}(x, t) & =U_{1}(\xi) \\
& =-\frac{3 k^{2} \epsilon}{\beta}\left(\lambda^{2}-4 \mu\right)\left[\frac{A_{1} \sinh \left(\frac{1}{2} \xi \sqrt{\lambda^{2}-4 \mu}\right)+A_{2} \cosh \left(\frac{1}{2} \xi \sqrt{\lambda^{2}-4 \mu}\right)}{A_{2} \sinh \left(\frac{1}{2} \xi \sqrt{\lambda^{2}-4 \mu}\right)+A_{1} \cosh \left(\frac{1}{2} \xi \sqrt{\lambda^{2}-4 \mu}\right)}\right]^{2}  \tag{22}\\
& +\frac{2 k^{4} \epsilon\left(\lambda^{2}-4 \mu\right)-\gamma k^{2}-\omega^{2}}{\beta k^{2}},
\end{align*}
$$

where $\xi=k x-\frac{\omega t^{\alpha}}{\Gamma(1+\alpha)}$.
In particular, if $\lambda=3, \mu=2, \epsilon=1, \gamma=-1, \beta=3, A_{1}=1, A_{2}=0, k=1$,
$\omega=1, \alpha=0.6$, then 22 becomes

$$
\begin{equation*}
u_{1}(x, t)=\frac{2}{3}-\tanh ^{2}\left(\frac{1}{2} x-\frac{t^{0.6}}{2 \Gamma(1.6)}\right) \tag{23}
\end{equation*}
$$

- case 2: $\lambda^{2}-4 \mu<0$, we get the trigonometric function solutions of Eq. 16)

$$
\begin{align*}
u_{2}(x, t) & =U_{2}(\xi) \\
& =-\frac{3 k^{2} \epsilon}{\beta}\left(4 \mu-\lambda^{2}\right)\left[\frac{A_{1} \sinh \left(\frac{1}{2} \xi \sqrt{4 \mu-\lambda^{2}}\right)+A_{2} \cosh \left(\frac{1}{2} \xi \sqrt{4 \mu-\lambda^{2}}\right)}{A_{2} \sinh \left(\frac{1}{2} \xi \sqrt{4 \mu-\lambda^{2}}\right)+A_{1} \cosh \left(\frac{1}{2} \xi \sqrt{4 \mu-\lambda^{2}}\right)}\right]^{2}  \tag{24}\\
& -\frac{2 k^{4} \epsilon\left(4 \mu-\lambda^{2}\right)+\gamma k^{2}+\omega^{2}}{\beta k^{2}},
\end{align*}
$$

where $\xi=k x-\frac{\omega t^{\alpha}}{\Gamma(1+\alpha)}$.
Also, if $\lambda=\sqrt{3}, \mu=1, k=1, \epsilon=1, \gamma=-1, \beta=3, A_{1}=0, A_{2}=1, k=1$, $\omega=1, \alpha=0.75$, then 24 becomes

$$
\begin{equation*}
u_{2}(x, t)=-\cot ^{2}\left(x-\frac{t^{0.75}}{\Gamma(1.75)}\right) \tag{25}
\end{equation*}
$$

- case 3: $\lambda^{2}-4 \mu=0$, we get the rational function solutions of Eq. 16

$$
\begin{equation*}
u_{3}(x, t)=U_{3}(\xi)=\frac{-\gamma k^{2}-\omega^{2}}{\beta k^{2}}-\frac{12 k^{2} \epsilon}{\beta}\left(\frac{A_{2}}{A_{2} \xi+A_{1}}\right)^{2} \tag{26}
\end{equation*}
$$

where $\xi=k x-\frac{\omega t^{\alpha}}{\Gamma(1+\alpha)}$.
If $\lambda=1, \mu=\frac{1}{4}, \epsilon=\frac{1}{4}, \gamma=-1, \beta=3, A_{1}=A_{2}=1, k=2, \omega=1, \alpha=1$, then

$$
\begin{equation*}
u_{3}(x, t)=\frac{1}{4}-\left(\frac{1}{1+2 x-t}\right)^{2} \tag{27}
\end{equation*}
$$


(a) $u_{1}(x, t)(\lambda=3, \mu=2, \epsilon=1$,
(b) $u_{2}(x, t)(\lambda=\sqrt{3}, \mu=1, \epsilon=1$,
$\left.A_{1}=1, A_{2}=0, k=1, \omega=1, \alpha=0.6\right)$
$\left.A_{1}=0, A_{2}=1, k=1, \omega=1, \alpha=0.75\right)$

(c) $u_{3}(x, t)\left(\lambda=1, \mu=\frac{1}{4}, \epsilon=\frac{1}{4}\right.$,

$$
\left.A_{1}=A_{2}=1, k=2, \omega=1, \alpha=1\right)
$$

Figure 1: 3DPlot of the exact solutions of Eq. (16) given by 23, 25) and 27 respectively, for $(x, t) \in[-10,10] \times[0,10]$.


Figure 2: 2DPlot of the exact solutions of Eq. 16 given by 23 , at $t=5$ and $x \in[-5,13]$, for $\alpha=0.6,0.85,1$.

## 4. Time-fractional Murray equation

Let's consider the (TFME) equation of the form:

$$
\begin{equation*}
\frac{\partial^{\alpha} u(x, t)}{\partial t^{\alpha}}-\frac{\partial^{2} u(x, t)}{\partial x^{2}}-a u(x, t) \frac{\partial u(x, t)}{\partial x}-b u(x, t)+c u(x, t)^{2}=0 \tag{28}
\end{equation*}
$$

where $a, b, c \in \mathbb{R}^{*}$ and $0<\alpha \leq 1$.
The fractional complex transformation $u(x, t)=U(\xi), \xi=k x-\omega \frac{t^{\alpha}}{\Gamma(1+\alpha)}$, transform the Eq. 28) to the following ordinary differential equation:

$$
\begin{equation*}
-\omega U^{\prime}-k^{2} U^{\prime \prime}-a k U U^{\prime}-b U+c U^{2}=0 \tag{29}
\end{equation*}
$$

By the same procedure as illustrated above, we can determine the value of $N$ by balancing $U^{\prime \prime}$ and $U U^{\prime}$ in Eq. 29.). We find $N=1$. We can suppose that the solutions of Eq. 29 is of the form:

$$
\begin{equation*}
U(\xi)=a_{0}+a_{1}\left(\frac{G^{\prime}(\xi)}{G(\xi)}\right) \tag{30}
\end{equation*}
$$

1. Let $G=G(\xi)$ satisfies (9).

Proceeding as above, we obtain a set of algebraic equations for $a_{0}, a_{1}, k, \omega, \lambda, \mu$.

$$
\begin{align*}
& -a_{0} b+a_{0}^{2} c-a_{1} \lambda k^{2} \mu+a a_{0} a_{1} k \mu+a_{1} \mu \omega=0 \\
& -a_{1} b+2 a_{0} a_{1} c-a_{1} \lambda^{2} k^{2}-2 a_{1} k^{2} \mu+a a_{0} a_{1} \lambda k+a a_{1}^{2} k \mu+a_{1} \lambda \omega=0 \\
& a_{1}^{2} c-3 a_{1} \lambda k^{2}+a a_{1}^{2} \lambda k+a a_{0} a_{1} k+a_{1} \omega=0  \tag{31}\\
& a a_{1}^{2} k-2 a_{1} k^{2}=0
\end{align*}
$$

Solving the system with the help of Mathematica 11, we get

$$
\begin{equation*}
\left\{a_{0} \rightarrow \frac{a b+2 c k \lambda}{2 a c}, a_{1} \rightarrow \frac{2 k}{a}, \omega \rightarrow \frac{-a^{2} b k-4 c^{2} k}{2 a c}, \mu \rightarrow \frac{4 c^{2} k^{2} \lambda^{2}-a^{2} b^{2}}{16 c^{2} k^{2}}\right\} \tag{32}
\end{equation*}
$$

Where $k$ and $\lambda$ are arbitrary constants. using Eqs. (32), the expression (30) can be written as:

$$
\begin{equation*}
U(\xi)=\frac{a b+2 c k \lambda}{2 a c}+\frac{2 k}{a}\left(\frac{G^{\prime}(\xi)}{G(\xi)}\right) \tag{33}
\end{equation*}
$$

With the fact that $\lambda^{2}-4 \mu=\lambda^{2}-\frac{4\left(4 c^{2} k^{2} \lambda^{2}-a^{2} b^{2}\right)}{16 c^{2} k^{2}}=\frac{a^{2} b^{2}}{4 c^{2} k^{2}}>0$, and using 11) then, the solution of (28) is in the form:

$$
\begin{equation*}
U(\xi)=\frac{b}{2 c}+\frac{b}{2 c}\left[\frac{A_{1} \sinh \left(\frac{a b}{4 c k} \xi\right)+A_{2} \cosh \left(\frac{a b}{4 c k} \xi\right)}{A_{2} \sinh \left(\frac{a b}{4 c k} \xi\right)+A_{1} \cosh \left(\frac{a b}{4 c k} \xi\right)}\right] \tag{34}
\end{equation*}
$$

where $\xi=k x+\frac{t^{\alpha}\left(a^{2} b k+4 c^{2} k\right)}{(2 a c) \Gamma(\alpha+1)}$.
After simplifying the expression (34), we get

$$
\begin{equation*}
u(x, t)=\frac{b}{2 c}+\frac{b}{2 c}\left[\frac{A_{1} \sinh \left(\frac{a b}{4 c} x+\frac{\left(a^{2} b^{2}+4 b c^{2}\right)}{8 c^{2} \Gamma(\alpha+1)} t^{\alpha}\right)+A_{2} \cosh \left(\frac{a b}{4 c} x+\frac{\left(a^{2} b^{2}+4 b c^{2}\right)}{8 c^{2} \Gamma(\alpha+1)} t^{\alpha}\right)}{A_{1} \cosh \left(\frac{a b}{4 c} x+\frac{\left(a^{2} b^{2}+4 b c^{2}\right)}{8 c^{2} \Gamma(\alpha+1)} t^{\alpha}\right)+A_{2} \sinh \left(\frac{a b}{4 c} x+\frac{\left(a^{2} b^{2}+4 b c^{2}\right)}{8 c^{2} \Gamma(\alpha+1)} t^{\alpha}\right)}\right] \tag{35}
\end{equation*}
$$

In particular case: if we take $a=b=2, c=1, A_{1} \neq 0, A_{2}=0, \alpha=0.5$, the solution (35) becomes

$$
\begin{equation*}
u(x, t)=1+\tanh \left(x+\frac{3 t^{0.5}}{\Gamma(1.5)}\right) \tag{36}
\end{equation*}
$$

And if: $a=b=2, c=1, A_{1}=0, A_{2} \neq 0, \alpha=1$, the solution (35) becomes

$$
\begin{equation*}
u(x, t)=1+\operatorname{coth}(x+3 t) \tag{37}
\end{equation*}
$$


(a) $u(x, t)\left(a=b=2, c=1, A_{2}=0, A_{1} \neq 0, \alpha=0.5\right)$
(b) $u(x, t)\left(a=b=2, c=1, A_{1}=0, A_{2} \neq 0, \alpha=1\right)$

Figure 3: 3DPlot of the exact solutions of Eq. 28) given by (36) and (37) respectively, for $(x, t) \in[-6,6] \times[0,1]$.
2. Let $G=G(\xi)$ satisfies (12).

Substituting Eq. (30) with using (12) into Eq. (29), collecting the coefficients of $(G(\xi))^{i},(i=0, \pm 1, \pm 2, \pm 3)$ and set it to zero, yields a set of algebraic equations for $a_{0}, a_{1}, k, \lambda, \omega$. These systems are:

$$
\begin{align*}
& -a_{1} b \nu-a_{0} b+2 a_{1}^{2} c \lambda \mu+a_{1}^{2} c \nu^{2}+2 a_{0} a_{1} c \nu+a_{0}^{2} c-2 a_{1} \lambda k^{2} \mu \nu=0, \\
& -a_{1} b \mu+2 a_{1}^{2} c \mu \nu+2 a_{0} a_{1} c \mu-2 a_{1} k^{2} \lambda \mu^{2}-a_{1} k^{2} \mu \nu^{2}-a a_{1}^{2} k \lambda \mu^{2} \\
& -a a_{1}^{2} k \mu \nu^{2}-a a_{0} a_{1} k \mu \nu-a_{1} \mu \nu \omega=0, \\
& a_{1}^{2} c \mu^{2}-3 a_{1} k^{2} \mu^{2} \nu-2 a a_{1}^{2} k \mu^{2} \nu-a a_{0} a_{1} k \mu^{2}-a_{1} \mu^{2} \omega=0, \\
& -2 a_{1} k^{2} \mu^{3}-a a_{1}^{2} k \mu^{3}=0,  \tag{38}\\
& -a_{1} b \lambda+2 a_{1}^{2} c \lambda \nu+2 a_{0} a_{1} c \lambda-2 a_{1} k^{2} \lambda^{2} \mu-a_{1} k^{2} \lambda \nu^{2}+a a_{1}^{2} k \lambda^{2} \mu+a a_{1}^{2} k \lambda \nu^{2} \\
& +a a_{0} a_{1} k \lambda \nu+a_{1} \lambda \nu \omega=0, \\
& a_{1}^{2} c \lambda^{2}-3 a_{1} k^{2} \lambda^{2} \nu+a_{1} \lambda^{2} \omega+2 a a_{1}^{2} k \lambda^{2} \nu+a a_{0} a_{1} k \lambda^{2}=0, \\
& a a_{1}^{2} k \lambda^{3}-2 a_{1} k^{2} \lambda^{3}=0 .
\end{align*}
$$

We obtain the roots of Eqs. (38) with the aid of Mathematica 11 as

$$
\begin{align*}
& \left\{a_{0} \rightarrow 0, a_{1} \rightarrow \frac{b}{c \nu}, k \rightarrow-\frac{a b}{2 c \nu}, \omega \rightarrow \frac{b\left(a^{2} b+4 c^{2}\right)}{4 c^{2} \nu}, \lambda \rightarrow 0\right\},  \tag{39}\\
& \left\{a_{0} \rightarrow \frac{b}{c}, a_{1} \rightarrow-\frac{b}{c \nu}, k \rightarrow \frac{a b}{2 c \nu}, \omega \rightarrow \frac{-a^{2} b^{2}-4 b c^{2}}{4 c^{2} \nu}, \lambda \rightarrow 0\right\} .
\end{align*}
$$

Now, substituting (39) and using Eq. (14) into (30), we obtain two exact traveling wave solutions of Eq. (28) as follows:

$$
\begin{equation*}
U_{1}(\xi)=-\frac{b}{A \mu c(\sinh (\nu \xi)+\cosh (\nu \xi))-c} \tag{40}
\end{equation*}
$$

where $\xi=-\frac{a b}{2 c \nu} x-\frac{b\left(a^{2} b+4 c^{2}\right)}{\Gamma(\alpha+1)\left(4 c^{2} \nu\right)} t^{\alpha}$.
If ( $a=2, b=c=1, \nu=1, \mu=1, A=1, \alpha=0.6$ ), then 40 becomes

$$
\begin{equation*}
u_{1}(x, t)=-\frac{1}{\cosh \left(-x-\frac{2 t^{0.6}}{\Gamma(1.6)}\right)+\sinh \left(-x-\frac{2 t^{0.6}}{\Gamma(1.6)}\right)-1}, \tag{41}
\end{equation*}
$$

or

$$
\begin{equation*}
U_{2}(\xi)=\frac{A \mu b(\sinh (\nu \xi)+\cosh (\nu \xi))}{A \mu c(\sinh (\nu \xi)+\cosh (\nu \xi))-c} \tag{42}
\end{equation*}
$$

where $\xi=\frac{a b}{2 c \nu} x+\frac{b\left(a^{2} b+4 c^{2}\right)}{\Gamma(\alpha+1)\left(4 c^{2} \nu\right)} t^{\alpha}$.
If ( $a=2, b=c=1, \nu=1, \mu=1, A=1, \alpha=1$ ), then (42) becomes

$$
\begin{equation*}
u_{2}(x, t)=\frac{\sinh (x+2 t)+\cosh (x+2 t)}{\sinh (x+2 t)+\cosh (x+2 t)-1} \tag{43}
\end{equation*}
$$


(a) $u_{1}(x, t)(a=2, b=c=1 \nu=\mu=1, A=1, \alpha=0.6)$
(b) $u_{2}(x, t)(a=2, b=c=1, \nu=\mu=1, A=1, \alpha=1)$

Figure 4: 3DPlot of the exact solutions of Eq. 28) given by 41 and 43 respectively, for $(x, t) \in[-10,10] \times[0,5]$.

## 5. The space-time fractional Phi-four equation

we study the following (STFPFE) in the form

$$
\begin{equation*}
\frac{\partial^{2 \alpha} u(x, t)}{\partial t^{2 \alpha}}-p \frac{\partial^{2 \beta} u(x, t)}{\partial x^{2 \beta}}-q u(x, t)+r u(x, t)^{3}=0, \tag{44}
\end{equation*}
$$

where $p, q, r \in \mathbb{R}_{+}^{*}$ and $\frac{1}{2}<\alpha \leq 1, \frac{1}{2}<\beta \leq 1$.
We see that the following fractional complex transformation $u(x, t)=U(\xi)$,
$\xi=\frac{k x^{\beta}}{\Gamma(1+\beta)}-\frac{\omega t^{\alpha}}{\Gamma(1+\alpha)}$, permit us converting the (STFGPFE) 44) to the (NLODE)

$$
\begin{equation*}
\left(\omega^{2}-k^{2} p\right) U^{\prime \prime}-q U+r U^{3}=0 \tag{45}
\end{equation*}
$$

Now, balancing the terms $U^{\prime \prime}$ and $U^{3}$ gives $N+2=3 N$, so that $N=1$ and thus we write

$$
\begin{equation*}
U(\xi)=a_{0}+a_{1}\left(\frac{G^{\prime}(\xi)}{G(\xi)}\right) \tag{46}
\end{equation*}
$$

1. Let $G=G(\xi)$ satisfies (9).

By following the same steps as above, Substituting Equation (46) with using (9) into Equation (45) and collecting all terms with the same order of $\left(\frac{G^{\prime}}{G}\right)$ together, Equating the coefficients of these terms to be zero, we obtain a set of algebraic equations for $a_{0}, a_{1},, k, \omega, \lambda, \mu$ as follow:

$$
\begin{align*}
& -a_{1} k^{2} \lambda \mu p+a_{1} \lambda \mu \omega^{2}+a_{0} q+a_{0}^{3} r=0, \\
& a_{1} \lambda^{2} k^{2}(-p)-2 a_{1} k^{2} \mu p+a_{1} \lambda^{2} \omega^{2}+2 a_{1} \mu \omega^{2}-a_{1} q+3 a_{0}^{2} a_{1} r=0,  \tag{47}\\
& -3 a_{1} \lambda k^{2} p+3 a_{1} \lambda \omega^{2}+3 a_{0} a_{1}^{2} r=0, \\
& -2 a_{1} k^{2} p+a_{1}^{3} r+2 a_{1} \omega^{2}=0
\end{align*}
$$

On solving the above set of algebraic equations, we have

$$
\begin{align*}
& \left\{a_{0} \rightarrow 0, a_{1} \rightarrow-\frac{\sqrt{2} \sqrt{k^{2} p-\omega^{2}}}{\sqrt{r}}, \lambda \rightarrow 0, \mu \rightarrow \frac{q}{2\left(\omega^{2}-k^{2} p\right)}\right\} \\
& \left\{a_{0} \rightarrow 0, a_{1} \rightarrow \frac{\sqrt{2} \sqrt{k^{2} p-\omega^{2}}}{\sqrt{r}}, \lambda \rightarrow 0, \mu \rightarrow \frac{q}{2\left(\omega^{2}-k^{2} p\right)}\right\} \tag{48}
\end{align*}
$$

By substituting (48) in (46) and using (11), because $\lambda^{2}-4 \mu=\frac{2 q}{k^{2} p-\omega^{2}}$, we distinguish two cases:

- if $k^{2} p-\omega^{2}>0$, we derive two solutions

$$
\begin{equation*}
U_{11}(\xi)=\sqrt{\frac{q}{r}}\left[\frac{A_{1} \sinh \left(\xi \sqrt{\frac{q}{2\left(k^{2} p-\omega^{2}\right)}}\right)+A_{2} \cosh \left(\xi \sqrt{\frac{q}{2\left(k^{2} p-\omega^{2}\right)}}\right)}{A_{2} \sinh \left(\xi \sqrt{\frac{q}{2\left(k^{2} p-\omega^{2}\right)}}\right)+A_{1} \cosh \left(\xi \sqrt{\frac{q}{2\left(k^{2} p-\omega^{2}\right)}}\right)}\right] \tag{49}
\end{equation*}
$$

or

$$
\begin{equation*}
U_{12}(\xi)=-\sqrt{\frac{q}{r}}\left[\frac{A_{1} \sinh \left(\xi \sqrt{\frac{q}{2\left(k^{2} p-\omega^{2}\right)}}\right)+A_{2} \cosh \left(\xi \sqrt{\frac{q}{2\left(k^{2} p-\omega^{2}\right)}}\right)}{A_{2} \sinh \left(\xi \sqrt{\frac{q}{2\left(k^{2} p-\omega^{2}\right)}}\right)+A_{1} \cosh \left(\xi \sqrt{\frac{q}{2\left(k^{2} p-\omega^{2}\right)}}\right)}\right], \tag{50}
\end{equation*}
$$

where $\xi=\frac{k x^{\beta}}{\Gamma(\beta+1)}-\frac{\omega t^{\alpha}}{\Gamma(\alpha+1)}$.
In particular, if $p=1, q=2=r, k=5, \omega=4, A_{1} \neq 0, A_{2}=0$,
$\alpha=0.6, \beta=0.8, ~ 50$ becomes

$$
\begin{equation*}
u_{12}(x, t)=-\tanh \left(\frac{5 x^{0.8}}{3 \Gamma(1.8)}-\frac{4 t^{0.6}}{3 \Gamma(1.6)}\right) . \tag{51}
\end{equation*}
$$

- If $k^{2} p-\omega^{2}<0$, we obtain two solutions

$$
\begin{equation*}
U_{21}(\xi)=i \sqrt{\frac{q}{r}}\left[\frac{A_{2} \cos \left(\xi \sqrt{\frac{q}{2\left(\omega^{2}-k^{2} p\right)}}\right)-A_{1} \sin \left(\xi \sqrt{\frac{q}{2\left(\omega^{2}-k^{2} p\right)}}\right)}{A_{2} \sin \left(\xi \sqrt{\frac{q}{2\left(\omega^{2}-k^{2} p\right)}}\right)+A_{1} \cos \left(\xi \sqrt{\frac{q}{2\left(\omega^{2}-k^{2} p\right)}}\right)}\right] \tag{52}
\end{equation*}
$$

or

$$
\begin{equation*}
U_{22}(\xi)=-i \sqrt{\frac{q}{r}}\left[\frac{A_{2} \cos \left(\xi \sqrt{\frac{q}{2\left(\omega^{2}-k^{2} p\right)}}\right)-A_{1} \sin \left(\xi \sqrt{\frac{q}{2\left(\omega^{2}-k^{2} p\right)}}\right)}{A_{2} \sin \left(\xi \sqrt{\frac{q}{2\left(\omega^{2}-k^{2} p\right)}}\right)+A_{1} \cos \left(\xi \sqrt{\frac{q}{2\left(\omega^{2}-k^{2} p\right)}}\right)}\right], \tag{53}
\end{equation*}
$$

where $\xi=\frac{k x^{\beta}}{\Gamma(\beta+1)}-\frac{\omega t^{\alpha}}{\Gamma(\alpha+1)}$.
Also, if $p=1, q=2=r, k=4, \omega=5, A_{1}=0, A_{2} \neq 0, \alpha=\beta=1$, the equation (53) becomes

$$
\begin{equation*}
u_{21}(x, t)=i \cot \left(\frac{4 x}{3}-\frac{5 t}{3}\right) \tag{54}
\end{equation*}
$$


(a) $u_{12}(x, t)(p=1, q=r=2, k=5, \omega=4$,
$\left.A_{1} \neq 0, A_{2}=0, \alpha=0.6, \beta=0.8\right)$

(b) $\left\|u_{21}(x, t)\right\|(p=1, q=r=2, k=4, \omega=5$,
$\left.A_{1}=0, A_{2} \neq 0, \alpha=\beta=1\right)$

Figure 5: 3DPlot of the exact solutions of Eq. (44) given by 51 and (54) respectively, for $(x, t) \in[0,5] \times[0,5]$.
2. Let $G=G(\xi)$ satisfies 12 .

Proceeding as above, substituting (46) with using 12 into 45 and equating the coefficients of $(G)^{i},(i=$ $0, i= \pm 1, i= \pm 2, i= \pm 3)$ to zero, yields a set of simultaneous algebraic equations among $a_{0}, a_{1}, k, \lambda, \omega$.

$$
\begin{align*}
& -2 a_{1} k^{2} \lambda \mu \nu p+2 a_{1} \lambda \mu \nu \omega^{2}-a_{1} \nu q-a_{0} q+6 a_{1}^{3} \lambda \mu \nu r+6 a_{1}^{2} a_{0} \lambda \mu r+a_{1}^{3} \nu^{3} r \\
& +3 a_{1}^{2} a_{0} \nu^{2} r+3 a_{1} a_{0}^{2} \nu r+a_{0}^{3} r=0, \\
& -2 a_{1} k^{2} \lambda \mu^{2} p-a_{1} k^{2} \mu \nu^{2} p+2 a_{1} \lambda \mu^{2} \omega^{2}+a_{1} \mu \nu^{2} \omega^{2}-a_{1} \mu q+3 a_{1}^{3} \lambda \mu^{2} r \\
& +3 a_{1}^{3} \mu \nu^{2} r+6 a_{0} a_{1}^{2} \mu \nu r+3 a_{0}^{2} a_{1} \mu r=0, \\
& -3 a_{1} k^{2} \mu^{2} \nu p+3 a_{1} \mu^{2} \nu \omega^{2}+3 a_{1}^{3} \mu^{2} \nu r+3 a_{0} a_{1}^{2} \mu^{2} r=0,  \tag{55}\\
& -2 a_{1} k^{2} \mu^{3} p+2 a_{1} \mu^{3} \omega^{2}+a_{1}^{3} \mu^{3} r=0, \\
& 2 a_{1} \lambda^{2} \mu \omega^{2}-2 a_{1} k^{2} \lambda^{2} \mu p-a_{1} k^{2} \lambda \nu^{2} p+a_{1} \lambda \nu^{2} \omega^{2}-a_{1} \lambda q+3 a_{1}^{3} \lambda^{2} \mu r \\
& +3 a_{1}^{3} \lambda \nu^{2} r+6 a_{0} a_{1}^{2} \lambda \nu r+3 a_{0}^{2} a_{1} \lambda r=0, \\
& 3 a_{1} \lambda^{2} \nu \omega^{2}-3 a_{1} k^{2} \lambda^{2} \nu p+3 a_{1}^{3} \lambda^{2} \nu r+3 a_{0} a_{1}^{2} \lambda^{2} r=0, \\
& 2 a_{1} \lambda^{3} \omega^{2}-2 a_{1} k^{2} \lambda^{3} p+a_{1}^{3} \lambda^{3} r=0 .
\end{align*}
$$

After solving these algebraic system, we get four sets of values of arbitrary constants:

$$
\begin{align*}
& \left\{a_{0} \rightarrow \frac{\sqrt{q}}{\sqrt{r}}, a_{1} \rightarrow-\frac{2 \sqrt{q}}{\nu \sqrt{r}}, \lambda \rightarrow 0, k \rightarrow-\frac{\sqrt{\nu^{2} \omega^{2}+2 q}}{\nu \sqrt{p}}\right\}, \\
& \left\{a_{0} \rightarrow \frac{\sqrt{q}}{\sqrt{r}}, a_{1} \rightarrow-\frac{2 \sqrt{q}}{\nu \sqrt{r}}, \lambda \rightarrow 0, k \rightarrow \frac{\sqrt{\nu^{2} \omega^{2}+2 q}}{\nu \sqrt{p}}\right\},  \tag{56}\\
& \left\{a_{0} \rightarrow-\frac{\sqrt{q}}{\sqrt{r}}, a_{1} \rightarrow \frac{2 \sqrt{q}}{\nu \sqrt{r}}, \lambda \rightarrow 0, k \rightarrow-\frac{\sqrt{\nu^{2} \omega^{2}+2 q}}{\nu \sqrt{p}}\right\}, \\
& \left\{a_{0} \rightarrow-\frac{\sqrt{q}}{\sqrt{r}}, a_{1} \rightarrow \frac{2 \sqrt{q}}{\nu \sqrt{r}}, \lambda \rightarrow 0, k \rightarrow \frac{\sqrt{\nu^{2} \omega^{2}+2 q}}{\nu \sqrt{p}}\right\} .
\end{align*}
$$

By substituting of $a_{0}, a_{1}, k$ from (56) with using (14) into (46), we derive four exact traveling wave solutions of Eq. 44

$$
\begin{equation*}
u_{1}(x, t)=U_{1}(\xi)=\frac{\sqrt{q}}{\sqrt{r}}\left[\frac{A \mu(\sinh (\nu \xi)+\cosh (\nu \xi))+1}{A \mu(\sinh (\nu \xi)+\cosh (\nu \xi))-1}\right] \tag{57}
\end{equation*}
$$

where $\xi=-\frac{\sqrt{\nu^{2} \omega^{2}+2 q}}{\Gamma(\beta+1)(\nu \sqrt{p})} x^{\beta}-\frac{\omega t^{\alpha}}{\Gamma(\alpha+1)}$.
In particular, $p=6, q=r=4, A=1, \mu=-1, \nu=2, \omega=2, \beta=0.9, \alpha=0.75$

$$
\begin{gather*}
u_{1}(x, t)=-\frac{1-\cosh \left(-\frac{2 x^{0.9}}{\Gamma(1.9)}-\frac{4 t^{0.75}}{\Gamma(1.75)}\right)-\sinh \left(-\frac{2 x^{0.9}}{\Gamma(1.9)}-\frac{4 t^{0.75}}{\Gamma(1.75)}\right)}{\cosh \left(-\frac{2 x^{0.9}}{\Gamma(1.9)}-\frac{4 t^{0.75}}{\Gamma(1.75)}\right)+\sinh \left(-\frac{2 x^{0.9}}{\Gamma(1.9)}-\frac{40^{0.75}}{\Gamma(1.75)}\right)+1}  \tag{58}\\
u_{2}(x, t)=U_{2}(\xi)=\frac{\sqrt{q}}{\sqrt{r}}\left[\frac{A \mu(\sinh (\nu \xi)+\cosh (\nu \xi))+1}{A \mu(\sinh (\nu \xi)+\cosh (\nu \xi))-1}\right] \tag{59}
\end{gather*}
$$

where $\xi=\frac{\sqrt{\nu^{2} \omega^{2}+2 q}}{\Gamma(\beta+1)(\nu \sqrt{p})} x^{\beta}-\frac{\omega t^{\alpha}}{\Gamma(\alpha+1)}$.

$$
\begin{equation*}
u_{3}(x, t)=U_{3}(\xi)=-\frac{\sqrt{q}}{\sqrt{r}}\left[\frac{A \mu(\sinh (\nu \xi)+\cosh (\nu \xi))+1}{A \mu(\sinh (\nu \xi)+\cosh (\nu \xi))-1}\right] \tag{60}
\end{equation*}
$$

where $\xi=-\frac{\sqrt{\nu^{2} \omega^{2}+2 q}}{\Gamma(\beta+1)(\nu \sqrt{p})} x^{\beta}-\frac{\omega t^{\alpha}}{\Gamma(\alpha+1)}$. Also

$$
\begin{equation*}
u_{4}(x, t)=U_{4}(\xi)=-\frac{\sqrt{q}}{\sqrt{r}}\left[\frac{A \mu(\sinh (\nu \xi)+\cosh (\nu \xi))+1}{A \mu(\sinh (\nu \xi)+\cosh (\nu \xi))-1}\right] \tag{61}
\end{equation*}
$$

where $\xi=\frac{\sqrt{\nu^{2} \omega^{2}+2 q}}{\Gamma(\beta+1)(\nu \sqrt{p})} x^{\beta}-\frac{\omega t^{\alpha}}{\Gamma(\alpha+1)}$.
In particular $p=6, q=r=4, A=1, \mu=-1, \nu=2, \omega=2, \beta=0.9, \alpha=0.75$

$$
\begin{equation*}
u_{4}(x, t)=U_{4}(\xi)=\frac{1-\cosh \left(\frac{2 x^{0.9}}{\Gamma(1.9)}-\frac{4 t^{0.75}}{\Gamma(1.75)}\right)-\sinh \left(\frac{2 x^{0.9}}{\Gamma(1.9)}-\frac{4 t^{0.75}}{\Gamma(1.75)}\right)}{\cosh \left(\frac{2 x^{0.9}}{\Gamma(1.9)}-\frac{4 t^{0.75}}{\Gamma(1.75)}\right)+\sinh \left(\frac{2 x^{0.9}}{\Gamma(1.9)}-\frac{4 t^{0.75}}{\Gamma(1.75)}\right)+1} . \tag{62}
\end{equation*}
$$

## 6. Conclusion

In this work we found the solutions of three important nonlinear time-fractional evolution equations, TFCBE, TFME and STFPFE.
We have used the $\left(\frac{G^{\prime}}{G}\right)$-expansion method to derive three types exact solutions (hyperbolic, trigonometric and rational solutions).
The availability of computer systems like Mathematica 11 facilitates the tedious algebraic calculations and plots of surfaces of solutions. The method which we have proposed in this paper is also a standard, direct and computerizable method, which allows us to do complicated and tedious algebraic calculation.
In general, $\left(\frac{G^{\prime}}{G}\right)$-expansion method is a very effective and powerful mathematical tool, can be further applied to solve various types of nonlinear fractional partial differential equations and also can be extended to physical mathematics, engineering and other nonlinear sciences.
We hope that these solutions will explain some nonlinear physical phenomena.


Figure 6: 3DPlot of the exact solutions of Eq. (44) given by $(58)$ and $(62)$ respectively, for $(x, t) \in[0,5] \times[0,3]$.

## References

[1] J. Akter, M.A. Akbar, Exact solutions to the Benney-Luke equation and the Phi-4 equations by using modified simple equation method, Results in Physics, Vol. 5 (2015), pp. 125-130.
[2] L. Bangqing, X. Meiping, M. Yulan, New exact solutions of (2+1)-dimensional generalization of shallow water wave equation by $\left(\frac{G^{\prime}}{G}\right)$-expansion method, Applied Mechanics and Materials, Vol. 20-23 (2010) pp. 1516-1521.
[3] R.M. Cherniha, New Ansätze and Exact Solutions for Nonlinear Reaction-Diffusion Equations Arising in Mathematical Biology, Symmetry in Nonlinear Mathematical Physics, 1 (1997) 138-146.
[4] R.M. Cherniha, New Exact Solutions Of One Nonlinear Equation In Mathematical Biology And Their Proprieties, Ukrainian Mathematical Journal, 53 (10) (2001) 1712-1727.
[5] M. Djilali, A. Hakem and A. Benali, Exact Solutions of Kupershmidt Equation, Approximate Solutions for Time-Fractional Kupershmidt Equation: A Comparison Study. International Journal of Analysis and Applications, 18 (3) (2020) pp. 493512.
[6] M. Djilali, A. Hakem, Solving Some Important Nonlinear Time-Fractional Evolution Equations By Using The (G'/G)Expansion Method, Journal of Science and Arts, 53 (4) (2020) pp. 815-832.
[7] M. Djilali, A. Hakem and A. Benali, A Comparison Between Analytical and Numerical Solutions for Time-Fractional Coupled Dispersive Long-Wave Equations, Fundamentals of Contemporary Mathematical Sciences 2 (1) (2021) pp. 8-29.
[8] Y. Guo, S. Lai, New exact solutions for an ( $\mathrm{N}+1$ )-dimensional generalized Boussinesq equation, Nonlinear Analysis, 72 (6) (2010) 2863-2873.
[9] O.V. Kaptsov, Construction Of Exact Solutions Of The Boussinesq Equation, Journal of Applied Mechanics and Technical Physics, 39 (3) (1998) 389-392.
[10] F. Mahmud, M. Samsuzzoha and M.A. Akbar, The generalized Kudryashov method to obtain exact traveling wave solutions of the PHI-four equation and the Fisher equation, Results in Physics, 7 (2017) 4296-4302.
[11] A. Malik, F. Chand, H. Kumar and S.C. Mishra, Exact solutions of some physical models using the ( $\frac{G^{\prime}}{G}$ )- expansion method. PRAMANA -journal of physics. Vol. 78, No. 4 (2012) pp. 513-529.
[12] D. Wang, W. Sun, C. Kong, H. Zhang, New extended rational expansion method and exact solutions of Boussinesq equation and Jimbo-Miwa equations, Applied Mathematics and Computation, 189 (1) (2007) 878-886.
[13] W. Hereman, A. Nuseir, Symbolic methods to construct exact solutions of nonlinear partial differential equations, Mathematics and Computers in Simulation, 43 (1) (1997) 13-27.
[14] A.M. Wazwaz, Analytic study on nonlinear variants of the RLW and the PHI-four equations, Communications in Nonlinear Science and Numerical Simulation, 12 (3) (2007) 314-327.
[15] S. Akcagi, T. Aydemir, Comparison between the $\left(\frac{G^{\prime}}{G}\right)$ - expansion method and the modified extended tanh method. Open Physics, 14 (2016) :88-94.
[16] P.A. Clarkson, New similarity solutions for the modified Boussinesq equation, Journal of Physics A: Mathematical and General, 22 (13) (1989) 2355-2367.
[17] D. Levi and P. Winternitz, Non-classical symmetry reduction: example of the Boussinesq equation, Journal of Physics A: Mathematical and General, 22 (15) (1989) 2915-2924.
[18] X. Deng, M. Zhao, X. Li, Travelling wave solutions for a nonlinear variant of the PHI-four equation, Mathematical and Computer Modelling, 49 (3-4) (2009) 617-622.
[19] A. Khajeh, M.M. Kabir, A.Y. Koma, New Exact and Explicit Travelling Wave Solutions for the Coupled Higgs Equation and a Nonlinear Variant of the PHI-four Equation, International Journal of Nonlinear Sciences \& Numerical Simulation, 11 (9) (2010) 725-741.
[20] M. Alquran, H.M. Jaradat, M.I. Syam, Analytical solution of the time-fractional Phi-4 equation by using modified residual power series method, Nonlinear Dynamics, 90 (2017) 2525-2529.
[21] S. Kumar and R. Singh, Exact and Numerical Solutions of Nonlinear Reaction ffusion Equation by Using the Cole-Hopf Transformation, International Transactions in Mathematical Sciences and Computer, 2 (2) (2009) pp. 241-252.
[22] M.T. Darvishia, M. Najafi, A.M. Wazwaz, Soliton solutions for Boussinesq-like equations with spatio-temporal dispersion, Ocean Engineering, 130 (2017) 228-240.
[23] R. Hirota, J. Satsuma, Nonlinear Evolution Equations Generated from the Backlund Transformation for the Boussinesq Equation, Progress of Theoretical Physics, 57 (3) (1977) 797-807.
[24] M. Alquran, and A. Qawasmeh, Soliton Solutions of Shallow Water Wave Equations by means of ( $\frac{G^{\prime}}{G}$ )-Expansion Method, Journal of Applied Analysis and Computation, 4 (3) (2014) pp. 221-229 .
[25] A. Bekir, Application of the $\left(\frac{G^{\prime}}{G}\right)$ - expansion method for nonlinear evolution equations. Physics Letters A 372 (19) (2008) 3400-3406.
[26] H. Naher, F.A. Abdullah, The Basic $\left(\frac{G^{\prime}}{G}\right)$-Expansion Method for the Fourth Order Boussinesq Equation. Applied Mathematics, 3 (2012) 1144-1152.
[27] E.J. Parkes, Observations on the basic $\left(\frac{G^{\prime}}{G}\right)$ - expansion method for finding solutions to nonlinear evolution equations. Applied Mathematics and Computation, 217 (4) (2010) 1759-1763.
[28] A.M. Shahoot, K.A .E. Alurrfi, M.O.M. Elmrid, A.M. Almsiri and A.M.H. Arwiniya, The $\left(\frac{G^{\prime}}{G}\right)$ - expansion method for solving a nonlinear PDE describing the nonlinear low-pass electrical lines. Journal Of Taibah University For Science ,13 (1) (2019) 63-70.
[29] Y. Shi, X. Li and B-G. Zhang, Traveling Wave Solutions of Two Nonlinear Wave Equations by ( $\frac{G^{\prime}}{G}$ )- expansion method. Advances in Mathematical Physics, Volume (2018) Article ID 8583418, 8 pages.
[30] M. Wang, X. Li, J. Zhang, The $\left(\frac{G^{\prime}}{G}\right)$ - expansion method and travelling wave solutions of nonlinear evolution equations in mathematical physics. Physics Letters A, 372 (4) (2008) 417-423.
[31] E.M.E. Zayed, THE $\left(\frac{G^{\prime}}{G}\right)$ - Expansion Method Combined With The Riccati Equation For Finding Exact Solutions Of Nonlinear PDEs. Journal of Applied Mathematics \& Informatics, Vol. 29, No. 1-2 (2011) pp. 351 - 367.
[32] W. Zhang, A Generalized Tanh-Function Type Method and the ( $\left.\frac{G^{\prime}}{G}\right)$ - expansion method for Solving Nonlinear Partial Differential Equations. Applied Mathematics, 4 (2013) 11-16
[33] G.W. Griffiths, W.E. Schiesser, Traveling Wave Analysis of Partial Differential Equations, Numerical and Analytical Methods with MATLAB and Maple. Elsevier Inc. (2012).
[34] P.A. Clarkson, D.K. Ludlow, Symmetry Reductions, Exact Solutions, and Painlevé Analysis for a generalized Boussinesq equation, Journal of Mathematical Analysis and Applications, 186 (1) (1994) 132-155.
[35] P.A. Clarkson, M.D. Kruskal, New similarity reductions of the Boussinesq equation, Journal of Mathematical Physics, 30 (1989) 2201-2213.
[36] O. Guner, Soliton solution of the generalized modified BBM equation and the generalized Boussinesq equation, Journal of Ocean Engineering and Science, 2 (4) (2017) 248-252.
[37] G. Barro, O. So, J.M. Ntaganda, B. Mampassi, B. Some, A numerical method for some nonlinear differential equation models in biology, Applied Mathematics and Computation, 200 (1) (2008) 28-33.
[38] J.D. Murray, Nonlinear Differential Equation Models in Biology, Clarendon Press, Oxford (1977).
[39] J.D. Murray, Mathematical Biology. Springer, Berlin (1989).
[40] M. Shkil, A. Nikitin and V. Boyko, Proceedings of the Second International Conference, Symmetry In Nonlinear Mathematical Physics. Institute of Mathematics of the National Academy of Sciences of Ukraine, Kyiv, Ukraine (1997).
[41] W. Gao, P. Veeresha, D.G. Prakasha, H.M. Baskonus and G. Yel, New Numerical Results for the Time-Fractional Phi-Four Equation Using a Novel Analytical Approach, Symmetry, 2020, 12 (3), 478; doi:10.3390/sym12030478.
[42] M. Najafi, Using He's Variational Method to Seek the Traveling Wave Solution of PHI-Four Equation, International Journal of Applied Mathematical Research, 1 (4) (2012) 659-665.
[43] R. Sassaman, A. Biswas, Soliton perturbation theory for phi-four model and nonlinear Klein-Gordon equations, Communications in Nonlinear Science and Numerical Simulation, 14 (8) (2009) 3239-3249.
[44] A-M. Wazwaz, Generalized forms of the phi-four equation with compactons, solitons and periodic solutions, Mathematics and Computers in Simulation, 69 (5-6) (2005) 580-588.
[45] A.A. Kilbas, H.M. Srivastava, and J.J. Trujillo, Theory and Applications of Fractional Differential Equations, Elsevier, Amsterdam, The Netherlands, (2006).
[46] K.B. Oldham and J. Spanier, The Fractional Calculus, Academic Press, New York, NY, USA (1974).
[47] I. Podlubny, Fractional Differential Equations, Academic Press, New York, NY, USA (1999).
[48] H. Afshari, E. Karapınar, A discussion on the existence of positive solutions of the boundary value problems via $\psi$-Hilfer fractional derivative on b-metric spaces, Advances in Difference Equations, (2020):616 https://doi.org/10.1186/s13662-020-03076-z.
[49] H. Afshari, E. Karapınar, A solution of the fractional differential equations in the setting of b-metric space, Carpathian Mathematical Publications, 13 (3) (2021) 764-774.
[50] Z.B. Li, J.H. He, Fractional Complex Transform for Fractional Differential Equations, Mathematical and Computational Applications, 15 (5), (2010) pp. 970-973.
[51] Z.B. Li, J.H. He, Application of the Fractional Complex Transform to Fractional Differential Equations, Nonlinear Science Letters A, 2 (3) (2011) pp. 121-126.
[52] T.T. Shone, A. Patra, Solution for Non-linear Fractional Partial Differential Equations Using Fractional Complex Transform, International Journal of Applied and Computational Mathematics, (2019) 5:90, https://doi.org/10.1007/s40819-019-0673-4.
[53] J.H. He and Z.B. Li, Converting Fractional Differential Equations Into Partial Differential Equations, Thermal Science, 16 (2) (2012) pp. 331-334.


[^0]:    Email addresses: djilalimedjahed@yahoo.fr (Medjahed Djilali), hakemali@yahoo.com (Ali Hakem)

